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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/753,403	01/09/2004	Dong-ryeol Park	033808-010	6389
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			3661	
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Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

·	Application No.	Applicant(s)			
	10/753,403	PARK ET AL.			
Office Action Summary	Examiner	Art Unit			
	Brian J. Broadhead	3661			
The MAILING DATE of this communication app Period for Reply	pears on the cover sheet with the c	correspondence address			
A SHORTENED STATUTORY PERIOD FOR REPL WHICHEVER IS LONGER, FROM THE MAILING D. - Extensions of time may be available under the provisions of 37 CFR 1.1 after SIX (6) MONTHS from the mailing date of this communication. - If NO period for reply is specified above, the maximum statutory period of Failure to reply within the set or extended period for reply will, by statute Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b).	ATE OF THIS COMMUNICATION 36(a). In no event, however, may a reply be tin will apply and will expire SIX (6) MONTHS from a cause the application to become ABANDONE	N. nely filed the mailing date of this communication. D (35 U.S.C. § 133).			
Status		•			
1) Responsive to communication(s) filed on 12 A	<u> </u>				
. ,—	This action is FINAL . 2b)⊠ This action is non-final.				
· · ·	Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under Ex parte Quayle, 1935 C.D. 11, 453 O.G. 213.				
closed in accordance with the practice under a	Ex parte Quayle, 1955 C.D. 11, 4.	00 O.G. 210.			
Disposition of Claims					
4) ⊠ Claim(s) 1-20 is/are pending in the application 4a) Of the above claim(s) is/are withdra 5) □ Claim(s) is/are allowed. 6) ☒ Claim(s) 1-20 is/are rejected. 7) □ Claim(s) is/are objected to. 8) □ Claim(s) are subject to restriction and/or	wn from consideration.				
Application Papers					
9) The specification is objected to by the Examine 10) The drawing(s) filed on is/are: a) accomposed and applicant may not request that any objection to the Replacement drawing sheet(s) including the correct 11) The oath or declaration is objected to by the Examine 11.	cepted or b) objected to by the drawing(s) be held in abeyance. Setion is required if the drawing(s) is ob	e 37 CFR 1.85(a). ejected to. See 37 CFR 1.121(d).			
Priority under 35 U.S.C. § 119					
12) ☐ Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f). a) ☐ All b) ☐ Some * c) ☐ None of: 1. ☐ Certified copies of the priority documents have been received. 2. ☐ Certified copies of the priority documents have been received in Application No 3. ☐ Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)). * See the attached detailed Office action for a list of the certified copies not received.					
Attachment(s) 1) Notice of References Cited (PTO-892) 2) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) Information Disclosure Statement(s) (PTO/SB/08)	4)	ate			
Paper No(s)/Mail Date	6)				

Application/Control Number: 10/753,403

Art Unit: 3661

DETAILED ACTION

Page 2

Claim Rejections - 35 USC § 103

- 1. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 2. Claims 1 through 20 are rejected under 35 U.S.C. 103(a) as being unpatentable over Goncalves et al. US 2004/0167670, in view of Junkins et al., 6266142.
- 3. Goncalves et al. disclose an image processing module (602) for calculating image coordinates at least one of the plurality of the light sources by detecting the light sources, controlled to flicker in response to the light source control signal, from an image signal obtained by a camera (this would be included in with the landmarks), a pose calculation module for calculating coordinates of the mobile robot using the calculated image coordinates and previously stored world coordinates of the light sources a motion control module for calculating a moving path for the mobile robot by applying the position coordinates of the mobile robot to previously stored spatial coordinates of the working space and controlling the mobile robot to move along the moving path; and a main control module for controlling interoperations of the modules and general operations of the mobile robot; further comprising a memory module for storing the world coordinates of the light sources, spatial coordinates of the mobile robot in the working space, and parameters calculated through camera calibration for compensating for distortion of a lens of the camera, wherein the pose calculation

Art Unit: 3661

module calculates translation and rotation of the robot by applying the image coordinates and the world coordinates to the specified position calculation algorithm, the pose calculation algorithm is a certain transformation matrix equation that is obtained by constructing an extension model for obtaining a translation and a rotation of the camera using a world coordinate system and a camera coordinate system and applying the extension model to a formula for compensating for distortion caused by a lens of the camera; the pose calculation module calculates translation and rotation of the robot by applying image coordinates and world coordinates to a certain pose calculation algorithm, an image processing module for detecting feature points of the light source, controlled to flicker through the communications module, from an image signal obtained by a camera; a motion control module for controlling the mobile robot to move under control of the main control module; and a memory module for storing parameters calculated through camera calibration for compensating for distortion caused by a lens of the camera, world coordinates of the light sources, and spatial coordinates of the mobile robot in a working space; wherein the pose calculation algorithm is a certain transformation matrix equation that is obtained by constructing an extension model for obtaining a translation and a rotation of the camera using a world coordinate system and a image coordinate system, and applying the extension model to a formula for

4. Goncalves et al. do not disclose a communications module for transmitting a light source control signal to selectively control flickering of a plurality of light sources of a

compensating for distortion caused by a lens of the camera, and the camera detects the

wavelength of the light source in paragraphs 75, 14, 160, 84, 51-56.

Application/Control Number: 10/753,403

Art Unit: 3661

landmark array provided in a working space; a landmark array comprising a plurality of light sources disposed in a certain area to selectively flicker; a landmark array control module for controlling the light sources of the landmark array to flicker; and an access point for receiving and processing the light source control signal transmitted from the mobile robot; the communications type used; and a light source control unit for controlling corresponding light sources to flicker in response to the light source control signal input from the access point.

Page 4

5. Junkins et al. teach a communications module for transmitting a light source control signal to selectively control flickering of a plurality of light sources of a landmark array provided in a working space on lines 14-20, on column 5; a landmark array comprising a plurality of light sources disposed in a certain area to selectively flicker on lines 40-55, on column 4; a landmark array control module for controlling the light sources of the landmark array to flicker (28); and an access point for receiving and processing the light source control signal transmitted from the mobile robot (82); and a light source control unit for controlling corresponding light sources to flicker in response to the light source control signal input from the access point on lines 14-20, on column 5. Junkins et al. inherently uses some type of wireless communications protocol. It would have been obvious to one of ordinary skill in art at the time the invention was made to use the beacons of Junkins et al. in the invention of Goncalves et al. because such modification would provide a non-contact measurement system that compensates for distance and environmental conditions as disclosed by Junkins et al.

Response to Arguments

Application/Control Number: 10/753,403 Page 5

Art Unit: 3661

6. Applicant's arguments with respect to claims 1-20 have been considered but are moot in view of the new ground(s) of rejection.

Conclusion

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Brian J. Broadhead whose telephone number is 571-272-6957. The examiner can normally be reached on Tuesday through Friday.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Thomas Black can be reached on 571-272-6956. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free). If you would like assistance from a USPTO Customer Service Representative or access to the automated information system, call 800-786-9199 (IN USA OR CANADA) or 571-272-1000.

Brian J. Broadhead

Examiner Art Unit 3661